# A glance at information-geometric signal processing

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# Information geometry in Statistical Signal Processing

Statistical signal processing (SSP) models data with distributions:

- ▶ parametric (Gaussians, histograms) [model size ~ D],
- ▶ semi-parametric (mixtures) [model size ~ kD],
- ▶ non-parametric (kernel density estimators [model size ~ n], Dirichlet/Gaussian processes [model size ~ D log n],)

 $Data = Pattern (\rightarrow information) + noise (independent)$ 

Paradigm of *computational information geometry* provides:

- Information (entropy), statistical invariance & geometry,
- Language of geometry for intuitive reasoning,
- Novel geometric algorithms for signal processing.

 $\rightarrow$  Intrinsic data analysis

# Example of information-geometric SSP (I)

Statistical distance: total Bregman divergence (tBD).



Shape Retrieval using Hierarchical Total Bregman Soft Clustering, IEEE Trans. Pattern Analysis and Machine Intelligence (PAMI), 2012.

# Example of information-geometric SSP (II)

DTI: diffusion ellipsoids interpreted as zero-centered Gaussian distributions.

total Bregman divergence (tBD).



(3D rat corpus callosum)

Total Bregman Divergence and its Applications to DTI Analysis, IEEE Trans. Medical Imaging (TMI), 2010.

## Statistical mixtures: Generative models of data sets

$$\label{eq:GMM} \begin{split} \mathsf{GMM} &= \textit{feature descriptor} \text{ for information retrieval (IR)} \\ &\rightarrow \text{classification [20], matching, etc.} \\ &\text{Increase dimension using color image patches.} \\ &\text{Low-frequency information encoded into compact statistical model.} \end{split}$$

 $\mathsf{Generative}\xspace$  model  $\rightarrow$  statistical image by GMM sampling.



 $\rightarrow$  A mixture  $\sum_{i=1}^{k} w_i N(\mu_i, \Sigma_i)$  is interpreted as a weighted point set in a parameter space:  $\{w_i, \theta_i = (\mu_i, \Sigma_i)\}_{i=1}^k$ .

#### Information-geometric hyperspectral imaging

Image with z-axis = spectral bands (radiance or reflectance).

- $\rightarrow$  characterize spectral variability, similarity and discrimination.
  - ► Normalize hyperspectral pixel vector (→histogram):

$$p_i = \frac{x_i}{\sum_{i=1}^L x_i}.$$

Spectral information divergence (single pixel):

$$SID(x, y) = D(x||y) + D(y||x),$$
  
$$D(p||q) = \sum_{i=1}^{L} p_i \log \frac{p_i}{q_i}$$

(aka. Jeffreys symmetrized Kullback-Leibler divergence [25])

C.-I. Chang, An information-theoretic approach to spectral variability, similarity, and discrimination for hyperspectral image analysis, IEEE Trans. Information Theory, 2000.

*Sided and symmetrized Bregman centroids*, IEEE Trans. Information Theory, 2009.

# Fisher-Rao Riemannian geometry (1945)

- ▶ *D*-parametric distribution family:  $\{p(x; \theta) | \theta \subseteq \mathbb{R}^D\}$ .
- Fisher Information matrix (FIM):

$$\begin{split} I(\theta) &= [I_{ij}], \ I_{ij} = E_{\theta} \left[ \frac{\partial \log p(x;\theta)}{\partial \theta_i} \frac{\partial \log p(x;\theta)}{\partial \theta_j} \right], \\ I(\theta) &= \operatorname{Var} \left[ \frac{\partial}{\partial \theta} \log p(x;\theta) \right] \succeq 0, \end{split}$$

always semi-positive definite:  $\forall x, x^T I(\theta) x \ge 0$ .

• Cramér-Rao lower bound (CRLB) for an unbiased estimator  $\hat{\theta}$ :

$$\operatorname{Var}[\hat{\theta}] \succeq I^{-1}(\theta)$$

Löwner ordering for cone of positive definite matrices:

 $A \succeq B \Leftrightarrow A - B \succeq 0.$ 

 $\rightarrow$  FIM interpreted as curvature of the log-likelihood function (= score function).

 $\rightarrow$  Estimation efficiency of  $\hat{\theta}$  depends on true hidden  $\theta$  parameter.

## Fisher-Rao Riemannian geometry (1945)

Rao chose the FIM for defining a statistical manifold  $|(\mathcal{M},g)|$ 

Infinitesimal length element:

$$\mathrm{d}s^2 = \sum_{ij} g_{ij}(\theta) \mathrm{d}\theta_i \mathrm{d}\theta_j = \mathrm{d}\theta^{\mathsf{T}} I(\theta) \mathrm{d}\theta$$

• Geodesic and distance are hard to explicitly calculate:

$$\rho(p(x;\theta_1), p(x;\theta_2)) = \min_{\substack{\theta(s)\\\theta(0)=\theta_1\\\theta(1)=\theta_2}} \int_0^1 \sqrt{\left(\frac{\mathrm{d}\theta}{\mathrm{d}s}\right)^T} I(\theta) \frac{\mathrm{d}\theta}{\mathrm{d}s} \mathrm{d}s$$

• Metric property of  $\rho$ , log/exp tangent/manifold mapping

#### $\rightarrow$ FR geometry limited from the viewpoint of computation.

# A particular case of Fisher-Rao Riemannian geometry

For location-scale families (normal, Cauchy, Laplace, uniform, elliptical):  $p(x; \mu, \sigma) = \frac{1}{\sigma} f\left(\frac{x-\mu}{\sigma}\right)$ . Fisher-Rao geometry amounts to hyperbolic geometry of constant curvature  $\kappa = -\frac{1}{(d-1)\beta}$  depending on the density profile:

$$\beta = \int \left( x \frac{f'(x)}{f(x)} + 1 \right)^2 f(x) \mathrm{d}x.$$

FR statistical Voronoi diagram [27] = Hyperbolic Voronoi diagram on parameter space.



#### Statistical invariance

Riemannian structure (M,g) on  $\{p(x;\theta) \mid \theta \in \Theta \subset \mathbb{R}^D\}$ 

θ-Invariance under non-singular parameterization:

$$\rho(p(x;\theta),p(x;\theta')) = \rho(p(x;\lambda(\theta)),p(x;\lambda(\theta')))$$

Normal parameterization  $(\mu, \sigma)$  or  $(\mu, \sigma^2)$  yields same distance

x-Invariance under different x-representation: Sufficient statistics (Fisher, 1922):

$$\Pr(X = x | t(X) = t, \theta) = \Pr(X = x | T(X) = t)$$

All information for  $\theta$  is contained in T.

→ Lossless information data reduction (exponential families). Markov kernel = statistical morphism (Chentsov 1972,[7, 8]). A particular Markov kernel is a deterministic mapping  $T: X \to Y$  with y = T(x),  $p_y = p_x T^{-1}$ .

#### Invariance if and only if g = Fisher information matrix

# f-divergences (1960's)

A statistical non-metric distance between two probability measures:

$$I_f(p:q) = \int f\left(\frac{p(x)}{q(x)}\right) q(x) \mathrm{d}x$$

f: continuous convex function with f(1) = 0, f'(1) = 0, f''(1) = 1.  $\rightarrow$  asymmetric (not a metric, except TV), modulo affine term.  $\rightarrow$  can always be symmetrized using  $s = f + f^*$ , with  $f^*(x) = xf(1/x)$ . include many well-known statistical measures: Kullback-Leibler,

 $\alpha$ -divergences, Hellinger, Chi squared, total variation (TV), etc.

*f*-divergences are the only statistical divergences that preserves equivalence wrt. sufficient statistic mapping:

$$I_f(p:q) \geq I_f(p_M:q_M)$$

with equality if and only if M = T (monotonicity property).

## Outline: Dually flat spaces

Statistical invariance also obtained using  $(M, g, \nabla, \nabla^*)$  where  $\nabla$  and  $\nabla^*$  are dual affine connections.

Riemannian structure (M, g) is particular case for  $\nabla = \nabla^* = \nabla^0$ , Levi-Civita connection:  $(M, g) = (M, g, \nabla^{(0)}, \nabla^{(0)})$ 

Dually flat space are algorithmically-friendly:

- Statistical mixtures of exponential families
- Learning & simplifying mixtures (k-MLE)
- Bregman Voronoi diagrams & dually  $\perp$  triangulations

#### Goal: Algorithmics of Gaussians/histograms wrt. Kullback-Leibler divergence.

#### Exponential Family Mixture Models (EFMMs)

Generalize Gaussian & Rayleigh MMs to many usual distributions.

$$m(x) = \sum_{i=1}^{k} w_i p_F(x; \lambda_i) \quad \text{with } \forall i \ w_i > 0, \sum_{i=1}^{k} w_i = 1$$

$$p_F(x;\lambda) = e^{\langle t(x),\theta\rangle - F(\theta) + k(x)}$$

F: log-Laplace transform (partition, cumulant function):

$$F(\theta) = \log \int_{x \in \mathcal{X}} e^{\langle t(x), \theta \rangle + k(x)} dx,$$

$$\theta \in \Theta = \left\{ \theta \; \bigg| \; \int_{x \in \mathcal{X}} e^{\langle t(x), \theta \rangle + k(x)} \mathrm{d}x < \infty \right\}$$

the natural parameter space.

- *d*: Dimension of the support  $\mathcal{X}$ .
- ▶ D: order of the family  $(= \dim \Theta)$ . Statistic:  $t(x) : \mathbb{R}^d \to \mathbb{R}^D$ .

# Statistical mixtures: Rayleigh MMs [37, 21] IntraVascular UltraSound (IVUS) imaging:



Coronary plaques: fibrotic tissues, calcified tissues, lipidic tissues **Rayleigh Mixture Models** (**RMMs**): for *segmentation* and *classification* tasks

# Statistical mixtures: Gaussian MMs [9, 21, 10]

Gaussian mixture models (GMMs): model low frequency. Color image interpreted as a 5D xyRGB point set.



$$\frac{\text{Gaussian distribution } p(x; \mu, \Sigma):}{\frac{1}{(2\pi)^{\frac{d}{2}}\sqrt{|\Sigma|}}} e^{-\frac{1}{2}D_{\Sigma^{-1}}(x-\mu,x-\mu)}}$$
Squared Mahalanobis distance:  

$$D_Q(x,y) = (x-y)^T Q(x-y)$$

$$x \in \mathbb{R}^d$$

$$d \text{ (multivariate)}$$

$$D = \frac{d(d+3)}{2} \text{ (order)}$$

$$\theta = (\Sigma^{-1}\mu, \frac{1}{2}\Sigma^{-1}) = (\theta_v, \theta_M)$$

$$\Theta = \mathbb{R} \times S_{++}^d$$

$$F(\theta) = \frac{1}{4}\theta_v^T \theta_M^{-1} \theta_v - \frac{1}{2}\log|\theta_M| + \frac{d}{2}\log \pi$$

$$t(x) = (x, -xx^T)$$

$$k(x) = 0$$

# Sampling from a Gaussian Mixture Model

To sample a variate x from a GMM:

- Choose a component / according to the weight distribution w<sub>1</sub>, ..., w<sub>k</sub>,
- Draw a variate x according to  $N(\mu_I, \Sigma_I)$ .
- $\rightarrow$  Sampling is a doubly stochastic process:
  - throw a biased dice with k faces to choose the component:

 $l \sim \text{Multinomial}(w_1, ..., w_k)$ 

- (Multinomial is also an EF, normalized histogram.)
- then draw at random a variate x from the *l*-th component

 $x \sim \text{Normal}(\mu_I, \Sigma_I)$ 

 $x = \mu + Cz$  with Cholesky:  $\Sigma = CC^T$  and  $z = [z_1 \dots z_d]^T$ standard normal random variate: $z_i = \sqrt{-2 \log U_1} \cos(2\pi U_2)$ 

#### Relative entropy for exponential families

- Distance between features (e.g., GMMs)
- Kullback-Leibler divergence (cross-entropy minus entropy):

$$\begin{split} \mathrm{KL}(P:Q) &= \int p(x)\log\frac{p(x)}{q(x)}\mathrm{d}x \geq 0\\ &= \underbrace{\int p(x)\log\frac{1}{q(x)}}_{H^{\times}(P:Q)} - \underbrace{\int p(x)\log\frac{1}{p(x)}}_{H(p)=H^{\times}(P:P)} \\ &= F(\theta_Q) - F(\theta_P) - \langle \theta_Q - \theta_P, \nabla F(\theta_P) \rangle\\ &= B_F(\theta_Q:\theta_P) \end{split}$$

Bregman divergence  $B_F$  defined for a strictly convex and differentiable function up to some affine terms.

• Proof  $KL(P : Q) = B_F(\theta_Q : \theta_P)$  follows from

$$X \sim E_F(\theta) \Longrightarrow E[t(X)] = \nabla F(\theta)$$

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#### Convex duality: Legendre transformation

▶ For a strictly convex and differentiable function  $F : \mathcal{X} \to \mathbb{R}$ :

$$F^*(y) = \sup_{x \in \mathcal{X}} \{ \underbrace{\langle y, x \rangle - F(x)}_{l_F(y;x);} \}$$

• Maximum obtained for  $y = \nabla F(x)$ :

$$abla_x I_F(y; x) = y - \nabla F(x) = 0 \Rightarrow y = \nabla F(x)$$

• Maximum *unique* from convexity of F ( $\nabla^2 F \succ 0$ ):

$$\nabla_x^2 I_F(y;x) = -\nabla^2 F(x) \prec 0$$

Convex conjugates:

$$(F, \mathcal{X}) \Leftrightarrow (F^*, \mathcal{Y}), \qquad \mathcal{Y} = \{\nabla F(x) \mid x \in \mathcal{X}\}$$

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Legendre duality: Geometric interpretation

Consider the epigraph of F as a convex object:

- convex hull (V-representation), versus
- half-space (*H*-representation).



#### Legendre transform also called "slope" transform.

## Legendre duality & Canonical divergence

Convex conjugates have *functional inverse* gradients

$$\nabla F^{-1} = \nabla F^*$$

 $\nabla F^*$  may require numerical approximation (not always available in analytical closed-form)

- Involution:  $(F^*)^* = F$  with  $\nabla F^* = (\nabla F)^{-1}$ .
- Convex conjugate  $F^*$  expressed using  $(\nabla F)^{-1}$ :

$$F^*(y) = \langle (\nabla F)^{-1}(y), y \rangle - F((\nabla F)^{-1}(y))$$

► Fenchel-Young inequality at the heart of canonical divergence:

$$F(x) + F^*(y) \ge \langle x, y \rangle$$

$$A_F(x:y) = A_{F^*}(y:x) = F(x) + F^*(y) - \langle x, y \rangle \ge 0$$

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# Dual Bregman divergences & canonical divergence [26]

$$\begin{aligned} \mathrm{KL}(P:Q) &= E_P\left[\log\frac{p(x)}{q(x)}\right] \geq 0 \\ &= B_F(\theta_Q:\theta_P) = B_{F^*}(\eta_P:\eta_Q) \\ &= F(\theta_Q) + F^*(\eta_P) - \langle \theta_Q, \eta_P \rangle \\ &= A_F(\theta_Q:\eta_P) = A_{F^*}(\eta_P:\theta_Q) \end{aligned}$$

with  $\theta_Q$  (natural parameterization) and  $\eta_P = E_P[t(X)] = \nabla F(\theta_P)$  (moment parameterization).

$$\mathrm{KL}(P:Q) = \underbrace{\int p(x) \log \frac{1}{q(x)} \mathrm{d}x}_{H^{\times}(P:Q)} - \underbrace{\int p(x) \log \frac{1}{p(x)} \mathrm{d}x}_{H(p)=H^{\times}(P:P)}$$

Shannon cross-entropy and entropy of EF [26]:

$$\begin{array}{lll} H^{\times}(P:Q) &=& F(\theta_Q) - \langle \theta_Q, \nabla F(\theta_P) \rangle - E_P[k(x)] \\ H(P) &=& F(\theta_P) - \langle \theta_P, \nabla F(\theta_P) \rangle - E_P[k(x)] \\ H(P) &=& -F^*(\eta_P) - E_P[k(x)] \end{array}$$

#### Bregman divergence: Geometric interpretation (I)

Potential function F, graph plot  $\mathcal{F}$ : (x, F(x)).

$$D_F(p:q) = F(p) - F(q) - \langle p-q, \nabla F(q) \rangle$$



#### Bregman divergence: Geometric interpretation (II)

Potential function f, graph plot  $\mathcal{F} : (x, f(x))$ .

$$B_f(p||q) = f(p) - f(q) - (p - q)f'(q)$$



 $B_f(.||q)$ : vertical distance between the hyperplane  $H_q$  tangent to  $\mathcal{F}$  at lifted point  $\hat{q}$ , and the translated hyperplane at  $\hat{p}$ .

## total Bregman divergence (tBD)

By analogy to least squares and total least squares total Bregman divergence (tBD) [13, 38, 14]

$$\delta_f(x,y) = \frac{b_f(x,y)}{\sqrt{1+\|\nabla f(y)\|^2}}$$



Proved statistical robustness of tBD.

#### Bregman sided centroids [25, 20]

Bregman centroids = unique minimizers of average Bregman divergences ( $B_F$  convex in right argument)

$$\bar{\theta} = \operatorname{argmin}_{\theta} \frac{1}{n} \sum_{i=1}^{n} B_{F}(\theta_{i} : \theta)$$

$$\bar{\theta}' = \operatorname{argmin}_{\theta} \frac{1}{n} \sum_{i=1}^{n} B_{F}(\theta : \theta_{i})$$

$$\bar{\theta} = \frac{1}{n} \sum_{i=1}^{n} \theta_{i}, \text{ center of mass, independent of } F$$
$$\bar{\theta}' = (\nabla F)^{-1} \left( \frac{1}{n} \sum_{i=1}^{n} (\nabla F)(\theta_{i}) \right)$$

#### $\rightarrow$ Generalized Kolmogorov-Nagumo *f*-means.

## Bregman divergences $B_F$ and $\nabla F$ -means

#### Bijection quasi-arithmetic means $(\nabla F) \Leftrightarrow$ Bregman divergence $B_F$ .

Bregman divergence B <sub>F</sub> (entropy/loss function F)	F	$\longleftrightarrow$	f = F'	$f^{-1} = (F')^{-1}$	<i>f</i> -mean (Generalized means)
Squared Euclidean distance (half squared loss)	$\frac{1}{2}x^{2}$	$\longleftrightarrow$	x	x	Arithmetic mean $\sum_{j=1}^{n} \frac{1}{n} x_j$
Kullback-Leibler divergence (Ext. neg. Shannon entropy)	$x \log x - x$	$\longleftrightarrow$	log x	exp x	Geometric mean $(\prod_{j=1}^{n} x_j)^{\frac{1}{n}}$
Itakura-Saito divergence (Burg entropy)	$-\log x$	$\longleftrightarrow$	$-\frac{1}{x}$	$-\frac{1}{x}$	Harmonic mean $\frac{n}{\sum_{j=1}^{n} \frac{1}{x_j}}$

 $\nabla F$  strictly increasing (like cumulative distribution functions)

Bregman sided centroids [25]

Two sided centroids  $\overline{C}$  and  $\overline{C}'$  expressed using two  $\theta/\eta$  coordinate systems: = 4 equations.

$$\begin{array}{rcl} \bar{C} & : & \bar{\theta}, \bar{\eta}' \\ \bar{C}' & : & \bar{\theta}', \bar{\eta} \end{array}$$

$$C: \bar{\theta} = \frac{1}{n} \sum_{i=1}^{n} \theta_i$$
$$\bar{\eta}' = \nabla F(\bar{\theta})$$
$$C': \bar{\eta} = \frac{1}{n} \sum_{i=1}^{n} \eta_i$$
$$\bar{\theta}' = \nabla F^*(\bar{\eta})$$

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# Bregman information [25]

Bregman information = minimum of loss function

$$\begin{split} I_F(\mathcal{P}) &= \frac{1}{n} \sum_{i=1}^n B_F(\theta_i : \bar{\theta}) \\ &= \frac{1}{n} \sum_{i=1}^n F(\theta_i) - F(\bar{\theta}) - \langle \theta_i - \bar{\theta}, \nabla F(\bar{\theta}) \rangle \\ &= \frac{1}{n} \sum_{i=1}^n F(\theta_i) - F(\bar{\theta}) - \left\langle \underbrace{\frac{1}{n} \sum_{i=1}^n \theta_i - \bar{\theta}, \nabla F(\bar{\theta})}_{=0} \right\rangle \\ &= J_F(\theta_1, ..., \theta_n) \end{split}$$

Jensen diversity index (e.g., Jensen-Shannon for  $F(x) = x \log x$ )

- For squared Euclidean distance, Bregman information = cluster variance,
- For Kullback-Leibler divergence, Bregman information related © 2012 Frank Nielsen, Sony Computer Science Laboratories, Inc.

## Bregman k-means clustering [5]

Bregman *k*-means: Find *k* centers  $C = \{C_1, ..., C_k\}$  that minimizes the loss function:

$$L_F(\mathcal{P}:\mathcal{C}) = \sum_{P \in \mathcal{P}} B_F(P:\mathcal{C})$$
$$B_F(P:\mathcal{C}) = \min_{i \in \{1,\dots,k\}} B_F(P:C_i)$$

 $\rightarrow$  generalize Lloyd' s quadratic error in Vector Quantization (VQ)

$$L_F(\mathcal{P}:\mathcal{C}) = I_F(\mathcal{P}) - I_F(\mathcal{C})$$

 $I_F(\mathcal{P}) \longrightarrow \text{total Bregman information} \\ I_F(\mathcal{C}) \longrightarrow \text{between-cluster Bregman information} \\ L_F(\mathcal{P}:\mathcal{C}) \longrightarrow \text{within-cluster Bregman information}$ 

total Bregman information = within-cluster Bregman information + between-cluster Bregman information

## Bregman k-means clustering [5]

$$I_F(\mathcal{P}) = L_F(\mathcal{P} : \mathcal{C}) + I_F(\mathcal{C})$$

Bregman clustering amounts to find the partition  $C^*$  that *minimizes* the <u>information loss</u>:

$$L_F^* = L_F(\mathcal{P} : \mathcal{C}^*) = \min_{\mathcal{C}} (I_F(\mathcal{P}) - I_F(\mathcal{C}))$$

Bregman k-means :

- Initialize distinct seeds:  $C_1 = P_1, ..., C_k = P_k$
- Repeat until convergence
  - Assign point *P<sub>i</sub>* to its closest centroid:

$$\mathcal{C}_i = \{ P \in \mathcal{P} \mid B_F(P : C_i) \le B_F(P : C_j) \; \forall j \neq i \}$$

• Update cluster centroids by taking their center of mass:  $C_i = \frac{1}{|C_i|} \sum_{P \in C_i} P.$ 

Loss function monotonically decreases and converges to a *local* optimum. (Extend to weighted point sets using barycenters.) © 2012 Frank Nielsen, Sony Computer Science Laboratories, Inc.

# Bregman k-means++ [1]: Careful seeding (only?!)

(also called Bregman k-medians since min  $\sum_i B_F^1(p_i : x)$ ). Extend the  $D^2$ -initialization of k-means++

Only seeding stage yields probabilistically guaranteed global approximation factor:

Bregman *k*-means++:

- Choose  $C = \{C_I\}$  for I uniformly random in  $\{1, ..., n\}$
- While  $|\mathcal{C}| < k$ 
  - ► Choose  $P \in \mathcal{P}$  with probability  $\frac{B_F(P:C)}{\sum_{i=1}^n B_F(P_i:C)} = \frac{B_F(P:C)}{L_F(\mathcal{P}:C)}$

→ Yields a  $O(\log k)$  approximation factor (with high probability). Constant in  $O(\cdot)$  depends on ratio of min/max  $\nabla^2 F$ .

#### Exponential family mixtures: Dual parameterizations

A finite weighted point set  $\{(w_i, \theta_i)\}_{i=1}^k$  in a statistical manifold. Many coordinate systems but two natural for computing:

- usual  $\lambda$ -parameterization or map  $\circ \lambda$ ,
- natural  $\theta$ -parameterization and dual  $\eta$ -parameterization.



Natural parameters Expectation parameters (KL distance invariant under non-degenerate reparameterization.)

# Maximum Likelihood Estimator (MLE)

Given n iid. observations  $x_1, ..., x_n$ Maximum Likelihood Estimator

$$\hat{\theta} = \operatorname{argmax}_{\theta \in \Theta} \prod_{i=1}^{n} p_{F}(x_{i}; \theta) = \operatorname{argmax}_{\theta \in \Theta} e^{\sum_{i=1}^{n} \langle t(x_{i}), \theta \rangle - F(\theta) + k(x_{i})}$$

is unique maximum since  $\nabla^2 F \succ 0$ . MLE equation:

$$\nabla F(\hat{\theta}) = \frac{1}{n} \sum_{i=1}^{n} t(x_i)$$

MLE is consistent, efficient with asymptotic normal distribution:  $\hat{\theta} \sim N\left(\theta, \frac{1}{n}I^{-1}(\theta)\right)$ Fisher information matrix for exponential families:

$$I(\theta) = \operatorname{var}[t(X)] = \nabla^2 F(\theta) = (\nabla^2 F^*(\eta))^{-1}$$

MLE may be biased (eg, normal distributions).  $\rightarrow$  called observed point  $\hat{P}$  in information geometry.

# Duality Bregman $\leftrightarrow$ Exponential families [5]



An exponential family...

$$p_F(x;\theta) = \exp(\langle t(x), \theta \rangle - F(\theta) + k(x))$$

has the log-density interpreted as a Bregman divergence:

$$\log p_F(x;\theta) = -B_{F^*}(t(x):\eta) + F^*(t(x)) + k(x)$$

Exponential families  $\Leftrightarrow$  Bregman divergences: Examples

Identify iso-distance contour as iso-probability contour (Bregman divergences always convex on rhs.)

F(x)	$p_F(x \theta)$	$\Leftrightarrow$	B <sub>F*</sub>
Generator	Exponential Family	$\Leftrightarrow$	Dual Bregman divergence
$x^2$	Spherical Gaussian	$\Leftrightarrow$	Squared loss
$x \log x$	Multinomial	$\Leftrightarrow$	Kullback-Leibler divergence
$x \log x - x$	Poisson	$\Leftrightarrow$	<i>I</i> -divergence
$-\log x$	Geometric	$\Leftrightarrow$	Itakura-Saito divergence
$\log  X $	Wishart	$\Leftrightarrow$	log-det/Burg matrix div. [39]

#### Maximum likelihood estimator revisited $\hat{\theta} = \arg \max_{\theta} \prod_{i=1}^{n} p_F(x_i; \theta)$

$$\begin{aligned} \max_{\theta} & \sum_{i=1}^{n} (\langle t(x_{i}), \theta \rangle - F(\theta) + k(x_{i})) \\ \max_{\theta} & \sum_{i=1}^{n} -B_{F^{*}}(t(x_{i}):\eta) + \underbrace{F^{*}(t(x_{i})) + k(x_{i})}_{\text{constant}} \\ \equiv \min_{\theta} & \sum_{i=1}^{n} B_{F^{*}}(t(x_{i}):\overline{\eta}) \end{aligned}$$

Right-sided Bregman centroid = center of mass:

$$\hat{\eta} = \frac{1}{n} \sum_{i=1}^{n} t(x_i)$$

 $\eta$ -MLE is center of mass of sufficient statistics  $\{y_i = t(x_i)\}_{i=1}^n$ .
Learning a mixture using the Expectation-Maximization [5]

- EM increases monotonically the expected complete likelihood L (or log-likelihood function I). (Marginalize the hidden variables z<sub>i</sub>'s)
- ► EM needs an initialization Θ<sub>0</sub>. (Usually by <u>k-means</u>: E.g., for each cluster we fit a Gaussian centered at the cluster centroid with covariance matrix the covariance of the cluster, and weight the relative proportion of points in that cluster.)
- EM needs a stopping criterion. EM keeps improving the expected log-likelihood. Need to break the loop when the difference of log-likelihood between successive iterations < threshold.

# Learning a mixture using the Expectation-Maximization [5, 13]

EM for EFMM is equivalent to a <u>Bregman soft clustering</u>. Bregman EM soft clustering algorithm on  $\{x_1, ..., x_n\}$ :

Initialization. Set  $\{w_i, \eta_i\}_{i=1}^k$  with  $\sum_{i=1}^k w_i = 1$ 

Loop until improvement < threshold.

**Expectation.** (compute posterior probabilities) For all observations *x* For all model components *i*:

Pr(i|x) = 
$$\frac{w_i e^{-B_{F^*}(x;\eta_i)}}{w_i e^{-B_{F^*}(x;\eta_i)}}$$

$$\Pr(I|X) = \frac{1}{\sum_{j=1}^{k} w_j e^{-B_{F^*}(x;\eta_j)}}$$

**Maximization.** For all model components *i*  $w_{i} = \frac{1}{n} \sum_{j=1}^{n} \Pr(i|x_{j})$   $\eta_{i} = \frac{\sum_{j=1}^{n} \Pr(i|x_{j})x_{j}}{\sum_{j=1}^{n} \Pr(i|x_{j})} \rightarrow \text{barycenter}$ 

### Monotonous convergence of the expected complete likelihood. !!! But sampling variates is a doubly stochastic process... !!!

### k-MLE for EFMM = Bregman Hard Clustering [18]

Bijection exponential families (distributions)  $\leftrightarrow$  Bregman distances

$$\log p_F(x;\theta) = -B_{F^*}(t(x):\eta) + F^*(t(x)) + k(x), \eta = \nabla F(\theta)$$

k-MLE (F) = Bregman hard k-means for  $F^*$  + cross-entropy minimization for weights Complete log-likelihood:

$$\begin{split} & \max_{\Theta} \sum_{i=1}^{n} \sum_{j=1}^{k} \delta_{j}(z_{i}) (\log p_{F}(x_{i}|\theta_{j}) + \log w_{j}) \\ & \min_{H} \sum_{i=1}^{n} \sum_{j=1}^{k} \delta_{j}(z_{i}) ((B_{F^{*}}(t(x_{i}):\eta_{j}) - \log w_{j}) \underbrace{-k(x_{i}) - F^{*}(t(x_{i}))}_{\text{constant}}) \\ & \equiv \min_{H} \sum_{i=1}^{n} \min_{j=1}^{k} B_{F^{*}}(t(x_{i}):\eta_{j}) - \log w_{j} \end{split}$$

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 $\rightarrow$  guarantees the (local) convergence of the *complete likelihood* of *k*-MLE. (Assign a sample to a unique cluster: Hard clustering).

# k-MLE for EFMMs [18]

- ▶ 0. Initialization: ∀i ∈ {1,...,k}, let w<sub>i</sub> = 1/k and η<sub>i</sub> = t(x<sub>i</sub>) (initialization is discussed later on).
- 1. Assignment:

 $\begin{array}{l} \forall i \in \{1,...,n\}, z_i = \operatorname{argmin}_{j=1}^k B_{F^*}(t(x_i) : \eta_j). \\ \text{Let } \mathcal{C}_i = \{x_j | z_j = i\}, \forall i \in \{1,...,k\} \text{ be the cluster partition} \end{array}$ 

- 2. Update the η-parameters:
   ∀i ∈ {1,...,k}, η<sub>i</sub> = 1/|C<sub>i</sub>| ∑<sub>x∈C<sub>i</sub></sub> t(x).
   Goto step 1 unless local convergence of the complete likelihood is reached.
- ▶ 3. Update the weights: ∀i ∈ {1, ..., k}, w<sub>i</sub> = 1/n |C<sub>i</sub>|.
   Goto step 1 unless local convergence of the complete likelihood is reached.
- $\rightarrow$  Steps 2 and 3 iterated until convergence: k-MLE = Hard EM  $\rightarrow$  Can use other k-means heuristics (like Hartigan greedy swap)

### Further generalization of k-MLE

### Each mixture component can have its own exponential family

Infinitely many families of exponential families:

- Weibull (incl. Rayleigh or exponential),
- generalized Gaussians (incl. normal, Laplace, uniform).

$$p(x; \mu, \alpha, \beta) = \frac{\beta}{2\alpha\Gamma(1/\beta)} \exp\left(-\frac{|x-\mu|^{\beta}}{\alpha}\right)$$

with  $\alpha > 0$  (scale parameter) and  $\beta > 0$  (shape parameter). Apply *k*-MLE by adding at each round a component family selection (eg., select the best  $\beta$  for each component).

k-MLE for mixtures of generalized Gaussians, ICPR, 2012. [36]

# k-MLE++ [18]

 k-MLE++ = Bregman F\* k-means++ initialization Guaranteed approximation on the best complete average log-likelihood.

 $\rightarrow$  Single step mixture learning (fast and good)

Indivisibility: Robustness when identifying statistical mixture models? Which k?

$$\forall k \in \mathbb{N}, \ N(\mu, \sigma^2) = \sum_{i=1}^k N\left(\frac{\mu}{k}, \frac{\sigma^2}{k}\right)$$

(add small perturbations  $\rightarrow$  we should cluster MMs to get compact high quality equivalent MMs)

➤ → Choose large k (like k = n for Kernel Density Estimators), and simplify MMs [9, 35]

### Speeding-up k-MLE... Fast assignment

Proximity data-structures for Bregman k-means:

$$\mathcal{C}_i = \{ P \in \mathcal{P} \mid B_F(P : C_i) \le B_F(P : C_j) \; \forall j \neq i \}$$

- Bregman Voronoi diagrams [6]
- Bregman Nearest Neighbors: ball trees [32] or vantage point trees [31].



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# Anisotropic Voronoi diagram (for MVN MMs) [12, 15]

From the source color image (a), we buid a 5D GMM with k = 32 components, and color each pixel with the mean color of the anisotropic Voronoi cell it belongs to. (~ weighted squared Mahalanobis distance per center)



### Voronoi diagrams



Voronoi diagram, dual  $\perp$  Delaunay triangulation (general position)

Bregman dual bisectors: Hyperplanes & hypersurfaces [6, 23, 27]

Right-sided bisector:  $\rightarrow$  Hyperplane ( $\theta$ -hyperplane)

$$H_F(p,q) = \{x \in \mathcal{X} \mid B_F(x:p) = B_F(x:q)\}.$$

 $H_F$  :

$$\langle \nabla F(p) - \nabla F(q), x \rangle + (F(p) - F(q) + \langle q, \nabla F(q) \rangle - \langle p, \nabla F(p) \rangle) = 0$$

<u>Left-sided bisector</u>:  $\rightarrow$  Hypersurface ( $\eta$ -hyperplane)

$$H'_F(p,q) = \{x \in \mathcal{X} \mid B_F(p:x) = B_F(q:x)\}$$

$$H'_F$$
:  $\langle \nabla F(x), q-p \rangle + F(p) - F(q) = 0$ 

# Visualizing Bregman bisectors



### Bregman Voronoi diagrams as minimization diagrams [6]

A subclass of affine diagrams which have all non-empty cells . Minimization diagram of the *n* functions  $D_i(x) = B_F(x : p_i) = F(x) - F(p_i) - \langle x - p_i, \nabla F(p_i) \rangle$ .  $\equiv$  minimization of *n* linear functions:

$$H_i(x) = (p_i - x)^T \nabla F(q_i) - F(p_i)$$







### Bregman dual Delaunay triangulations





Delaunay

Exponential

Hellinger-like

- empty Bregman sphere property,
- geodesic triangles.

BVDs extends Euclidean Voronoi diagrams with similar complexity/algorithms.

### Non-commutative Bregman Orthogonality

3-point property (generalized law of cosines):

$$B_F(p:r) = B_F(p:q) + B_F(q:r) - (p-q)^T (\nabla F(r) - \nabla F(q)))$$



 $(pq)_{\theta}$  Bregman orthogonal to  $(qr)_{\eta}$  iff.

$$B_F(p:r) = B_F(p:q) + B_F(q:r)$$

(Equivalent to  $\langle \theta_p - \theta_q, \eta_r - \eta_q \rangle = 0$ ) Extend Pythagoras theorem

$$(pq)_{\theta} \perp_F (qr)_{\eta}$$

### $\rightarrow \perp_F$ is not commutative...

... except in the squared Euclidean/Mahalanobis case, © 2012 Fray Nielsen, Spny Computer Science Laboratories, Inc.

### Dually orthogonal Bregman Voronoi & Triangulations

Ordinary Voronoi diagram is perpendicular to Delaunay triangulation.

Dual line segment geodesics:

$$egin{array}{rll} (arphi q)_{ heta}&=&\{ heta= heta_{m p}+(1-\lambda) heta_{m q}\;|\lambda\in[0,1]\}\ (arphi q)_{\eta}&=&\{\eta=\eta_{m p}+(1-\lambda)\eta_{m q}\;|\lambda\in[0,1]\} \end{array}$$

Bisectors:

$$\begin{array}{ll} B_{\theta}(p,q) & : & \langle x,\theta_{q}-\theta_{p}\rangle + F(\theta_{p}) - F(\theta_{q}) = 0 \\ B_{\eta}(p,q) & : & \langle x,\eta_{q}-\eta_{p}\rangle + F^{*}(\eta_{p}) - F^{*}(\eta_{q}) = 0 \end{array}$$

Dual orthogonality:

$$egin{array}{rcl} & {\mathcal B}_\eta(p,q) & \perp & (pq)_\eta \ & (pq)_ heta & \perp & {\mathcal B}_ heta(p,q) \end{array}$$

Dually orthogonal Bregman Voronoi & Triangulations



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### Simplifying mixture: Kullback-Leibler projection theorem

An exponential family mixture model  $\tilde{p} = \sum_{i=1}^{k} w_i p_F(x; \theta_i)$ Right-sided KL barycenter  $\bar{p}^*$  of components interpreted as the *projection* of the mixture model  $\tilde{p} \in \mathcal{P}$  onto the model exponential family manifold  $\mathcal{E}_F$  [34]:



manifold of probability distribution

### Right-sided KL centroid = Left-sided Bregman centroid

### Left-sided or right-sided Kullback-Leibler centroids?

- Left/right Bregman centroids=Right/left entropic centroids (KL of exp. fam.) Left-sided/right-sided centroids: *different* (statistical) properties:
  - Right-sided entropic centroid: zero-avoiding (cover support of pdfs.)
  - Left-sided entropic centroid: zero-forcing (captures highest mode).



# Hierarchical clustering of GMMs (Burbea-Rao)

Hierarchical clustering of GMMs wrt. Bhattacharyya distance. Simplify the number of components of an initial GMM.



### Two symmetrizations of Bregman divergences

Jeffreys-Bregman divergences.

$$S_F(p;q) = \frac{B_F(p,q) + B_F(q,p)}{2}$$
$$= \frac{1}{2} \langle p - q, \nabla F(p) - \nabla F(q) \rangle,$$

Jensen-Bregman divergences (diversity index).

$$J_{F}(p;q) = \frac{B_{F}(p, \frac{p+q}{2}) + B_{F}(q, \frac{p+q}{2})}{2}$$
  
=  $\frac{F(p) + F(q)}{2} - F\left(\frac{p+q}{2}\right) = BR_{F}(p,q)$ 

Skew Jensen divergence [20, 29]  $J_F^{(\alpha)}(p;q) = \alpha F(p) + (1-\alpha)F(q) - F(\alpha p + (1-\alpha)q) = BR_F^{(\alpha)}(p;q)$ (Jeffreys and Jensen-Shannon symmetrization of Kullback-Leibler)

### (Burbea-Rao centroids ( $\alpha$ -skewed Jensen centroids)

Minimum average divergence

OPT: 
$$c = \arg \min_{x} \sum_{i=1}^{n} w_i J_F^{(\alpha)}(x, p_i) = \arg \min_{x} L(x)$$

Equivalent to minimize:

$$E(c) = \left(\sum_{i=1}^{n} w_i \alpha\right) F(c) - \sum_{i=1}^{n} w_i F(\alpha c + (1-\alpha)p_i)$$

Sum E = F + G of convex F + concave G function  $\Rightarrow$ Convex-ConCave Procedure (CCCP) Start from arbitrary  $c_0$ , and iteratively update as:

$$abla F(c_{t+1}) = -
abla G(c_t)$$

 $\Rightarrow$  guaranteed convergence to a local minimum.



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Iterative algorithm for Burbea-Rao centroids

Apply CCCP scheme

$$\nabla F(c_{t+1}) = \sum_{i=1}^{n} w_i \nabla F(\alpha c_t + (1-\alpha)p_i)$$

$$c_{t+1} = \nabla F^{-1} \left( \sum_{i=1}^{n} w_i \nabla F \left( \alpha c_t + (1-\alpha) p_i \right) \right)$$

Get arbitrarily fine approximations of the (skew) Burbea-Rao centroids and barycenters.

Unique GLOBAL minimum when divergence is separable [20]. Unique GLOBAL minimum for matrix mean [22] for the logDet divergence.

### Statistical divergences (Recap.)

- ► Kullback-Leibler is a *f*-divergence (→ statistical invariance, information monotonicity, curved geometry)
- Kullback-Leibler of exponential families = Bregman divergences on parameters (dually flat geometry)
- Skew Jensen-divergence (Burbea-Rao, α = 1/2) include Bregman divergences in limit cases [20]
- No known closed form for Kullback-Leibler of mixtures. But closed-form for EFMMs with the Cauchy-Schwarz divergence [17]:

$$\mathrm{CS}(P:Q) = -\log \frac{\int p(x)q(x)\mathrm{d}x}{\sqrt{\int p(x)^2\mathrm{d}x \int q(x)^2\mathrm{d}x}}$$

Closed-Form Information-Theoretic Divergences for Statistical Mixtures, ICPR, 2012.

# Summary

### Computational information-geometric signal processing:

- Statistical manifold (M, g): Rao's distance and Fisher-Rao curved riemannian geometry.
- Statistical manifold (M, g, ∇, ∇\*): dually flat spaces, Bregman divergences, geodesics are straight lines in either θ/η parameter space.
- Clustering & learning statistical mixtures (EM=soft Bregman clustering, k-MLE, KDE simplification, hierarchical mixtures [11])
- ► Software library: JMEF [9] (Java), PYMEF [33] (Python)
- ... but also many other geometry to explore: Hilbertian, Finsler [3], Kähler, Wasserstein, etc. (it is easy to require non-Euclidean geometry but then space is wild open!)

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### Exponential families & statistical distances

Universal density estimators [2] generalizing Gaussians/histograms (single EF density approximates any smooth density) Explicit formula for

- Shannon entropy, cross-entropy, and Kullback-Leibler divergence [26]:
- Rényi/Tsallis entropy and divergence [28]
- ▶ Sharma-Mittal entropy and divergence [30]. A 2-parameter family extending extensive Rényi (for  $\beta \rightarrow 1$ ) and non-extensive Tsallis entropies (for  $\beta \rightarrow \alpha$ )

$$\mathcal{H}_{lpha,eta}(p) = rac{1}{1-eta} \left( \left(\int p(x)^lpha \mathrm{d}x 
ight)^{rac{1-eta}{1-lpha}} - 1 
ight),$$

with  $\alpha > 0, \alpha \neq 1, \beta \neq 1$ .

- Skew Jensen and Burbea-Rao divergence [20]
- Chernoff information and divergence [16]
- Mixtures: total Least square, Jensen-Rényi, Cauchy-Schwarz divergence [17].

### Statistical invariance: Markov kernel

Probability family:  $p(x; \theta)$ .

 $(X,\sigma)$  and  $(X',\sigma')$  two measurable spaces.

 $\sigma$ : A  $\sigma$ -algebra on X

(non-empty, closed under complementation and countable union).

Markov kernel = transition probability kernel  $K: X \times \sigma' \rightarrow [0, 1]$ :

- ▶  $\forall E' \in \sigma', K(\cdot, E')$  measurable map,
- $\forall x \in X, K(x, \cdot)$  is a probability measure on  $(X', \sigma')$ .

p a pm. on  $(X, \sigma)$  induces Kp a pm., with

$$\mathsf{Kp}(\mathsf{E}') = \int_{\mathsf{X}} \mathsf{K}(\mathsf{x}, \mathsf{E}') \mathsf{p}(\mathrm{d}\mathsf{x}), \forall \mathsf{E}' \subset \sigma'$$

Space of Bregman spheres and Bregman balls [6] Dual Bregman balls (bounding Bregman spheres):

$$\begin{array}{rcl} \operatorname{Ball}_F^r(c,r) &=& \{x \in \mathcal{X} \mid B_F(x:c) \leq r\} \\ \operatorname{and} & \operatorname{Ball}_F^r(c,r) &=& \{x \in \mathcal{X} \mid B_F(c:x) \leq r\} \end{array}$$

Legendre duality:



Illustration for Itakura-Saito divergence,  $F(x) = -\log x$ 

Space of Bregman spheres: Lifting map [6]

 $\mathcal{F}: x \mapsto \hat{x} = (x, F(x))$ , hypersurface in  $\mathbb{R}^{d+1}$ .

 $H_p$ : Tangent hyperplane at  $\hat{p}$ ,  $z = H_p(x) = \langle x - p, 
abla F(p) 
angle + F(p)$ 

- Bregman sphere  $\sigma \longrightarrow \hat{\sigma}$  with supporting hyperplane  $H_{\sigma}: z = \langle x c, \nabla F(c) \rangle + F(c) + r$ . (// to  $H_c$  and shifted vertically by r)  $\hat{\sigma} = \mathcal{F} \cap H_{\sigma}$ .
- intersection of any hyperplane H with F projects onto X as a Bregman sphere:

$$H: z = \langle x, a \rangle + b \to \sigma : \operatorname{Ball}_F(c = (\nabla F)^{-1}(a), r = \langle a, c \rangle - F(c) + b)$$

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